Progression of Maximum Power Point Tracking for Photovoltaic

Jenifer.A [a], Y.Sukhi [b], S.Anita[c], A.Fayaz Ahamed [d]

[a,b,c,d]R.M.K. Engineering College

Abstract

In a recent survey, Indian authorities has proposed to generate 20000 MW grid-based solar strength, by way of the 12 months 2020. To make use of the most power from PV panel maximum power point tracking method is used. This paper offers a reference and gives the progression of diverse MPPT methods in photovoltaic energy generation. The one-of-a-kind strategies for MPPT strategies are discussed. From the sooner methods to current techniques are taken from literature and dealt. Since the I-V curve of PV is chaotic the usage of energy string optimizers is likewise explained.

Keywords: Maximum power point tracking (MPPT), photovoltaic (PV)

1. Introduction

In current years renewable energy assets such as solar, wave and wind are used for the generation of energy. Photovoltaic (PV) generation is getting an increasing number of   crucial as a renewable supply because of the blessings including the absence of gas price, little preservation and no noise and put on because of absence of shifting parts. The measure of force produced from a photovoltaic (PV) framework chiefly relies upon the components, like temperature and irradiances. Consequently an excessive cost PV ought to be operated on the maximum strength factor (MPP) which adjustments with solar irradiances. Hence it is important to track the maximum operating point of PV. Many MPPT approaches are accessible which shift in intricacy, sensors required, combination speed, cost, scope of viability, execution equipment, prevalence, and in different regards.

2. Problem Definition

Figure 1 shows the I-V characteristics of a PV panel. The principle objective with MPPT method is to naturally discover the voltage V_{MPP} or current I_{MPP} at which a PV exhibit ought to work to acquire the greatest force yield P_{MPP} under a given temperature and irradiance. It's far referred to that in partial shading situations, in some instances it is possible to have multiple neighborhood maxima, but normal there may be nonetheless most effective one genuine MPP. Maximum techniques react to modifications in both irradiance and temperature, yet some are explicitly greater treasured if temperature is kind of regular. Most procedures would certainly react to adjustments within the showcase because of maturing; however a few are open-circle and might require occasional adjusting. The cluster will ordinarily be associated with a force converter that can fluctuate the current coming from the PV exhibit.

The key point of the paper is to give a total reference to MPPT strategies and subsequently to utilize power string streamlining agents to screen the complete yield of the exhibit and constantly change the introduced burden to keep the framework activity at its pinnacle proficiency point.
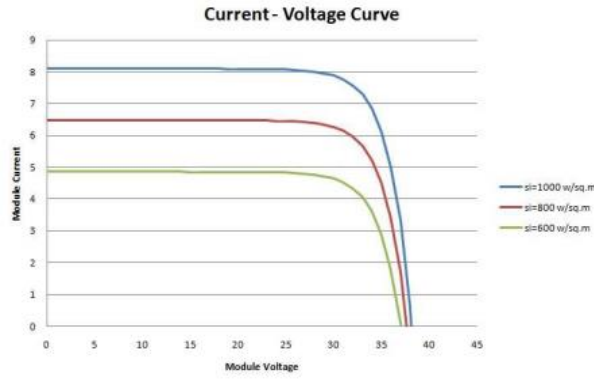
Fig 1 I-V characteristics of PV

3. MPPT Methods

The various MPPT methods are given in order below from the earliest.

A. Perturb & Observe (P & O) method

The common utilized MPPT is P and O. It depends on the rules:- if the working voltage of the PV cluster is bothered in a provide guidance and if the force drawn from the PV exhibit expands, this implies that the working point has moved towards the MPP and the working voltage should be additionally irritated a similar way. If the force drawn from the PV cluster diminishes, the working point has moved away from the MPP and along these lines the course of the working voltage bother should be changed. P&O techniques can bomb under quickly changing barometrical conditions. Fig 2 shows the flowchart for P and O strategy.

B. (i) Incremental Conductance (INC) method

The INC algorithm is extensively used because of the excessive monitoring accuracy at regular state and exact adaptability to rapidly atmospheric condition. The incremental conductance method is based totally at the slope of the PV array power curve (Fig 3).
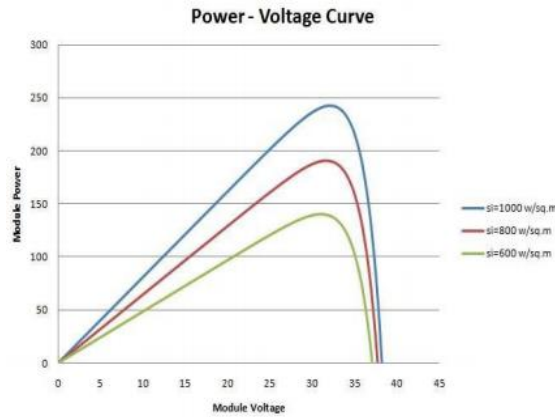

Fig 3 P-V curve of PV

At the MPP slope is zero, left of MPP -positive and right on MPP - negative, as given

$\delta P/\delta V = 0$, at MPP

$\delta P/\delta V > 0$, left of MPP

$\delta P/\delta V < 0$, rightof MPP.　　　　　(1)

(1) can be rewritten as

$\delta I/\delta V = -I/V$, at MPP

$\delta I/\delta V > -I/V$, left of MPP

$\delta I/\delta V < -I/V$, right of MPP.　　　(2)

The MPP would thus be able to be followed by contrasting the momentary conductance (I/V) to the gradual conductance ($\delta I/\delta V$). V_{ref} is the reference voltage at which the PV exhibit is compelled to work. At the MPP, V_{ref} equivalents to VMPP. When the MPP is reached, the activity of the PV exhibit is kept up now except if a change in ΔI is noted, showing a change in air conditions and the MPP. The calculation decrements or augmentations Vref to follow the new MPP. The augmentation length comes to a decision how quick the MPP is observed.
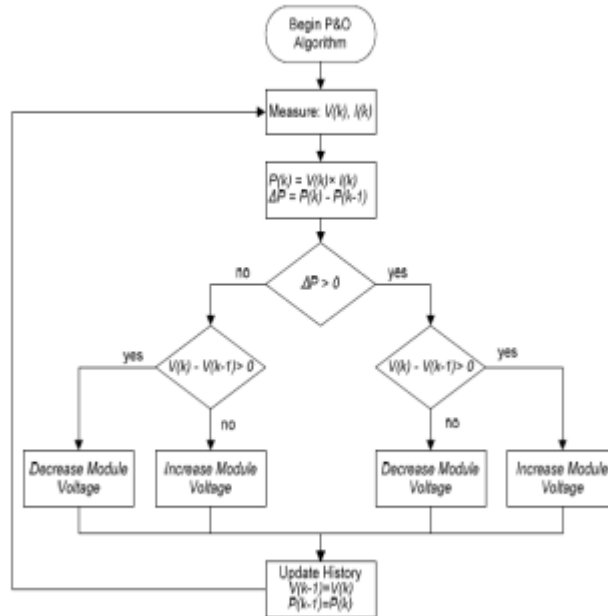

Fig 2 Flowchart for P & O

(ii)Variable step size Incremental Conductance method

Variable advance size INC consequently changes the progression size to follow the PV cluster greatest force point. Contrasted and the ordinary fixed advance size technique, this approach can viably rise the MPPT fast and precision all the while. The progression size for INC MPPT strategy is for the most part stable. The force drawn from the PV exhibit with a bigger advance size contributes to quicker elements however exorbitantly consistent state motions adds to quicker elements yet inordinate consistent state motions bringing about a similarly low proficiency. The present circumstance is recessed when algorithm is working with a more modest advance size. Hence the MPPT with fixed advance size should create a good tradeoff between the elements can be settled with variable advance size emphasis. This method is straightforward & effective manner to enhance monitoring accuracy in addition to monitoring dynamic variable step length followed to reduce the problem is

$$\delta(j) = \delta(j-1) \pm M^* \, dp/dv \qquad (3)$$

Where M – Scaling factor. M essentially determines the performances of MPPT system. Flowchart is shown in Fig 4.
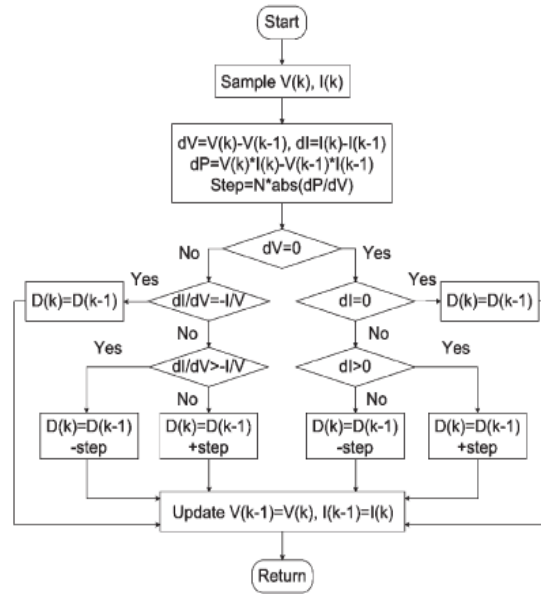
Fig 4 Flowchart for variable step size INC

C. Fuzzy control strategy

Dual mode fuzzy control approach (Fig 6) with a regulating element meet specific necessities of accuracy and for rapidly varying atmospheric conditions. It combines rough tuning and particular tuning fuzzy control with regulating factor consistent voltage tracking (CVT), P&O, INC, Curve fitting approach will become tough to attain the extent of excessive manipulate accuracy, speedy monitoring and there's no oscillation close to MPP because of non-linear characteristics of PV cells. MPPT controller with fuzzy method has brilliant features like proper robustness and flexibility, no necessities on correct version of the item and may triumph over the nonlinear issues of the output effectively. To follow the MPP precisely and quickly when the working spot is far away from MPP, the regulator picks the unpleasant tuning mode. A fast following would be normal then again, when the framework works close to the MPP. The regulator picks the exact tuning mode, stable force yield and precise situating would be more important to diminish the swaying. Consequently harsh tuning and exact tuning fluffy control techniques can be consolidated to frame another double mode fluffy control system. With this new technique the yield voltage and current are identified first and afterward the yield force can be acquired. As per the yield force's alters of sufficiency and course, the harsh tuning mode and exact tuning mode will be choose consequently by utilizing the connection between power 'P' and obligation cycle 'D'. At last, through the changing the obligation cycle persistently the yield force can watch out for greatest when δP/δD =0, the yield power makes certain to arrive at the most extreme. Fig 5 shows the P-D relation curve.
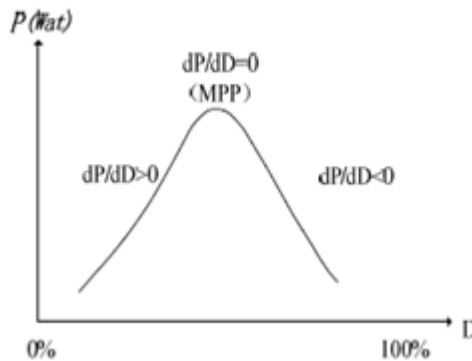

Fig 5 P-D relation curve

When K1< $\Delta\rho / \Delta D < K2$,system works in precise tuning mode, otherwise it works in rough tuning mode.
Regulating factor: $\Delta D = [\propto \in +(1-\propto) \in C] syn\ (ECE)$ (4)

$\Delta P(n) = E$ $\Delta P(n)\Delta D = EC$ (5) $\Delta D\ (n+1) = \Delta D$ (6)

Rule E is a, EC is B, $\Delta D\ is\ C$.A, B, C fuzzy subsets

D. Incremental Resistance (INR) method

The number one distinction among this set of rules and the others is that the step-length modes of the INR MPPT can be switched by using extreme values/factors of a threshold functions that is a manufactured from the exponential of the PV array output energy (Pn) and absolutely the cost of the PV array energy derivate δP/δI as

$$C = P^n * \left| \frac{dP}{dI} \right| \qquad (7)$$

This method is capable of improve no longer best the consistent nation performance however also the dynamic reaction. The concept can be formulated with the aid of

δC/δI ≥ 0, stable variable step-size mode

(left of MPP)

δC/δI < 0, Variable step-size mode

(left of MPP)

δC/δI > 0, Variable step-size mode

(right of MPP)

δC/δI ≤ 0, stable variable step-size mode

(right of MPP)　　　　　(8)

The variable step-size INR method is also based on the fact that the slope of the PV array power curve (Figure 5) is zero at the MPP, positive at the left of the MPP, and negative at the right, as given by

δP/δI = 0, at MPP

δP/δI > 0, left of MPP

δP/δI < 0, right of MPP.　　　　　(9)

Since $\frac{dP}{dI} = \frac{d(IV)}{dI} = V + I \frac{dV}{dI} = V + I \frac{\Delta V}{\Delta I}$

(9) can be rewritten as

δV/δI = −V/I, at MPP

δV/δI > −V/I, left of MPP

δV/δI < −V/I, right of MPP.　　　(10)

The MPP can subsequently be tracked by way of using comparing the at once resistance with the INR (δV/δI), as proven inside the flowchart. I_{ref} is the reference present day at which the PV array is forced to carry out. on the MPP, I_{ref} is equal to IMPP. As soon as the MPP is reached, the operation of the PV array is maintained at this factor till a change in ΔV is stated, indicating a trade in atmospheric situations on the MPP. The set of regulations decreases or increases The variable step- length technique solves the format hassle satisfying tradeoff amongst the dynamic and oscillations.

E. Particle Swarm Optimization (PSO)

PSO procedure is generally utilized for partial concealing. This fundamentally diminish the energy yield of PV.PSO approach is fit for following worldwide MMP under Partial concealed conditions. P& O neglects to follow worldwide MPPT when irradiance changed out of nowhere. INC offers better following exhibitions however swaying around the MPP. It is a populace based pursuit technique. Calculation keeps a multitude of people (called particles) where every Particle addresses an up-and-comer arrangement. Particles follow a basic conduct to imitate the accomplishment of adjoining particles and its own triumphs accomplished. The situation of a molecule is impacted by the best molecule in an area just as the best arrangement found by a molecule.

For MPPT, in an order to start the optimization, a solution vector of global current with N_p particle can be defined as:

$$x_i^k = I_g = [Ig_1, Ig_2, \ldots \ldots Ig_j] \qquad (13)$$

Where　　　　　　　　j　　　　　　　= 1,2 …. N_p objective　　　　　　function　　　　　　is
$$f(x_i^k) > f(y_i)$$

Power from PV array often varies due to partial shading. Hence, in such cases, the particles must be reinitialized to search the new global point. Therefore; following condition is used to reinitialize the particles

$$|\frac{Px_{(i+1)}-Px_{(i)}}{Px_{(i)}}| > \Delta P \qquad (14)$$

PSO shows satisfactorily tracks the worldwide point for each non shading & shading circumstance.

F. Estimate – Perturb – Perturb (EPP) Method

EPP is Estimate – Perturb – Perturb which makes use of estimate manner for every two perturbs techniques for finding maximum PV output. on this method, the perturb manner conducts the search over the exceptionally non-linear PV feature, and the estimate technique compensates the perturb device for irradiance changing situations. This method improves the tracking accuracy and speed of the MPPT manages as compared available techniques.

P&O set of rules is easy to put into impact it has brief comings similar to the PV device can't usually feature at the most energy point due to the sluggish trial and errors procedure and as a end result the sun power from the PV arrays are not genuinely implemented and the operation of the PV machine may additionally fail to music the MPP due to surprising adjustments in sunshine. The open and quick – circuit modern-day approach is based on measured terminal voltage and current-day of PV arrays. It gives rapid reaction and do no longer purpose oscillations is regular state. the net dimension of open – circuit voltage or quick circuit contemporary motives a reduction in output.INC set of rules has speedy tracking manner. Fuzzy true judgment or neural community controls can song the maximum strength issue online. but these controls are the immoderate fee of implementation. In changed P & O method resolve the climbing incorrect directions through decoupling the PV strength fluctuations as a result of irradiance changing. This EPP approach provides an irradiance changing estimate process in every perturb system to degree the amount of power change because of the trade of atmospheric condition and then compensates it in the perturb technique. There are two operation mode named. Mode 1 for estimate method and mode 2 for perturb method. Comparing with the MP&O approach, the EPP technique has a monitoring speed of 1.5 instances faster. it can provide accurate and reliable maximum electricity tracking overall performance even below a swiftly converting irradiance condition.

G. Genetic Algorithm

MPPT with genetic set of rules measures open circuit voltage and short circuit contemporary then gives directly and unexpectedly the top of the line voltage so the converter duty cycle may be adjusted. GA's are optimization stochastic algorithms based on herbal genetic choice. It does not work with a factor however with a populace of points. Fig 7 indicates description of the algorithm. With GA, modifications in atmospheric situations isn't uncovered due to the fact the set of rules gives immediately the MPP in less than one 2nd and the facts within the application change for each atmospheric situation. The oscillations across the MPP are likewise solved while compared with INC balance.
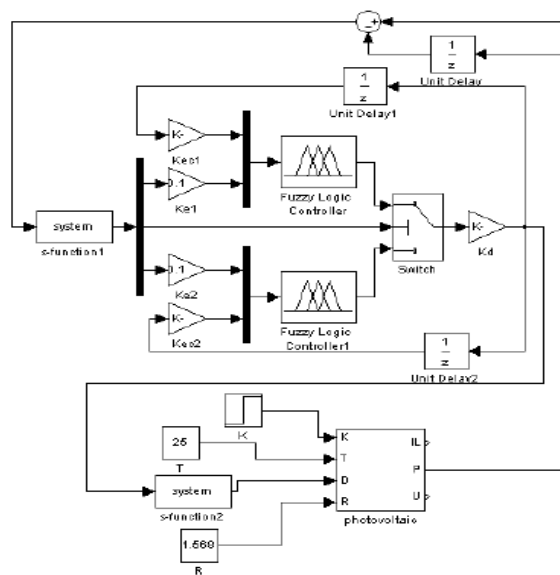

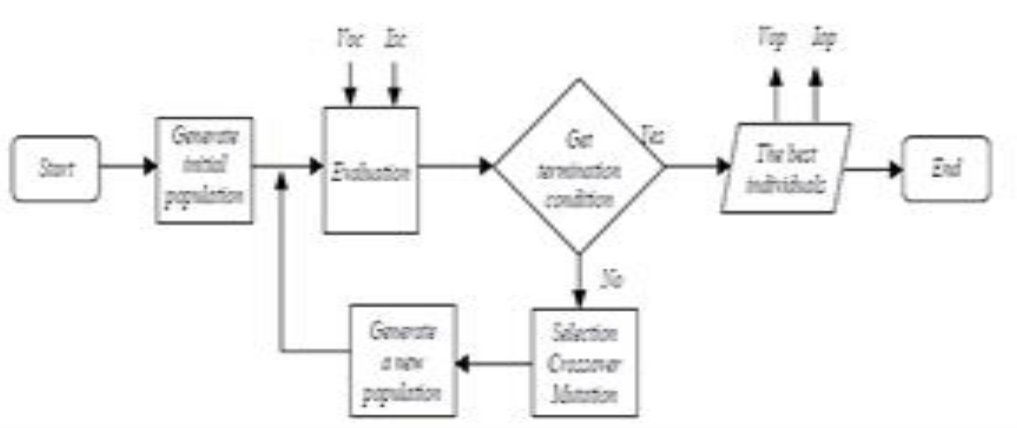**Fig 6** Dual mode fuzzy control system
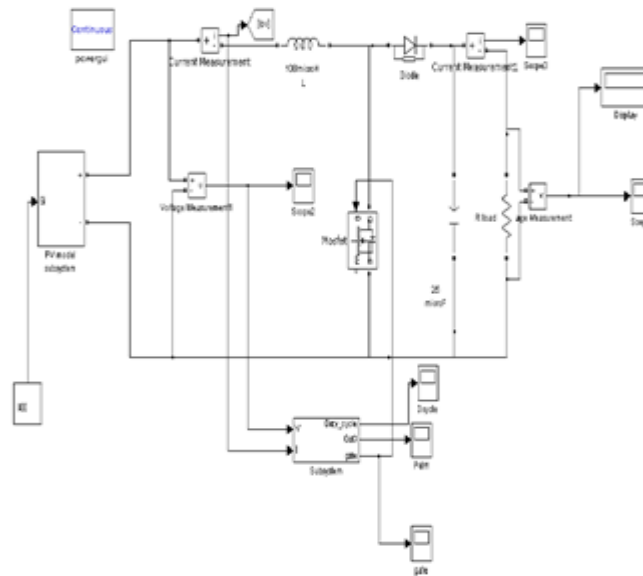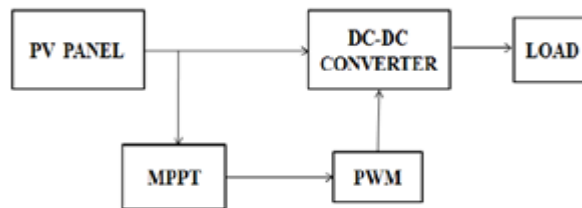
Fig7 Description of the algorithm

Figure 8 Simulation diagram of INC

Simulation was done in Matlab package and the simulation results for INC are shown below. The block diagram is as follows

The values for which the simulation done is tabulated

Open circuit voltage Voc	21.4V
Short circuit current Isc	6.41A
Maximum output power	100W
Voltage at maximum power	17.4V
Current at maximum power	5.75A

Table 1 Data's of solar panel

When simulated using INC algorithm it observed that the PV is operating at its maximum voltage and current. The output power obtained is maximum and it is shown in Output power of the PV panel is maximum when simulated at 800W/m2. Hence the efficiency of the system improves. INC finds the MPP accurately at changing atmospheric conditions also. The simulation circuit is shown in figure 8.The obtained PV voltage and current without MPPT and with MPPT is shown in figure 9,10,11 and 12.It can be observed that PV is operating at its maximum power point when INC is used. Simulation was carried for 3 different methods.
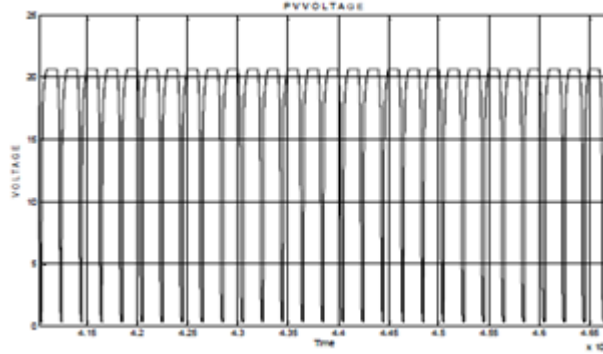
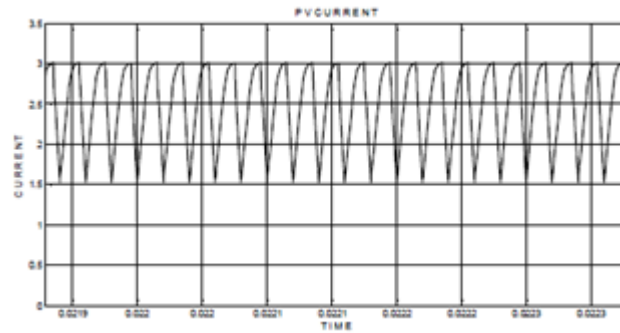

Figure 9 Output voltage of PV without MPPT

Figure 10 Output current of PV without MPPT

4. Power Optimizers

The DC yield from PV board is changed over to AC by inverters. In huge scope PV, boards are associated in arrangement to frame strings and from strings parallel string inverters are associated. The disadvantage to this methodology is that MPPT framework must be applied to the cluster overall. Since the current voltage is chaotic, a board even somewhat shadowed can have drastically lower yield, and significantly increment its inside opposition. As the boards are wired in arrangement, this would make the yield of the whole string be decreased because of the expanded complete obstruction. This adjustment in execution makes the MPPT framework change the activity point, moving the remainder of the boards from their best presentation. As a result of their consecutive wiring, power crisscross between PV modules inside a string can prompt an extraordinary and lopsided loss of force from the whole sunlight based cluster, now and again prompting total framework disappointment.

A power optimizer is a DC to DC converter generation developed to maximize the electricity harvest from solar photovoltaic. They do this with the aid of in my opinion tuning the overall performance of the panel thru maximum strength factor monitoring, and optionally tuning the output to fit the overall performance of the string inverter. Power optimizers are especially beneficial while the general overall performance of the energy generating additives in a dispensed device will range significantly, variations in gadget, shading of moderate or wind, or being mounted dealing with specific directions or widely separated locations. String optimizers are deployed in big-scale PV structures to lower price and boom performance. This optimized gadget has two times the form of modules regular with string and better resolution MPP monitoring than conventional systems without strength optimizers. More modules in line with string lower the amount of combiners by way of manner of fifty percent and decrease the quantity of cabling which results in tremendous electric powered balance of gadget monetary savings. Putting MPPT on each string will boom lifetime device manufacturing.
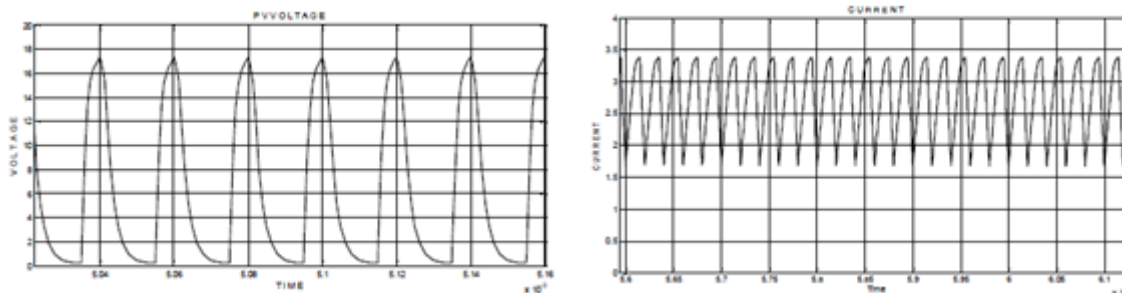
Figure 11, 12 Output voltage & Output   current of PV with MPPT

5. Conclusion

A few MPPT procedures taken from the writing are talked about and discussed in this, with their upsides and downsides. With a very much planned framework including an appropriate converter and choosing a proficient and demonstrated calculation, the execution of MPPT is straightforward and can be effortlessly developed to accomplish a satisfactory productivity level of the PV modules. This paper gives an overview of all MPPT techniques and also focuses on power string optimizers which are essential for large PV panels

References

[1]   Joe-Air Jiang, Tsong-Liang Huang, Ying-Tung Hsiao, Chia-Hong Chen (2005),"Maximum Power Tracking for Photovoltaic Power Systems", Tamkang Journal   of Science and Engineering, vol. 8, no 2, pp. 147-153.

[2]   Marcelo Gradella Villalva, Jonas Rafael Gazoli, and Ernesto Ruppert Filho (2009),"Comprehensive Approach to Modeling and Simulation of Photovoltaic Arrays",   IEEE Transactions on Power Electronics, vol.24, no. 5.

[3]   Nicola Femia,Giovanni Petrone, Giovanni Spagnuolo,Massimo Vitelli(2005),"Optimization of Perturb and Observe Maximum Power Point Tracking Method", IEEE Transactions on Power Electronics, vol. 20, no. 4.

[4]   Syafaruddin, E. Karatepe, T. Hiyama "Artificial neural network-polar coordinated fuzzy controller based maximum power point tracking control under partially shaded conditions" IET Renew. Power Gener., 2009, Vol. 3, Iss. 2, pp. 239–253 239 doi: 10.1049/iet-rpg:20080065

[5]   Fang Luo , Pengwei Xu , Yong Kang , Shangxu Duan" A Variable Step Maximum Power Point Tracking Method Using Differential Equation Solution" 1-4244-0737-0/07/$20.00_c 2007 IEEE

[6]   Moreno, A. Julve, J. Silvestre, S. and Castaner, L., "A fuzzy logic controller for stand alone PV systems", Photovoltaic Specialists Conference, 2000. Conference Record of the Twenty-Eighth IEEE, pp. 1618-1621, 2000.

[7]   Xiao, W and Dunford, W.G., "A modified adaptive hill climbing MPPT method for photovoltaic power systems," 35th Annual PowerElectronics Specialists Conference, 2004. PESC 04. IEEE Volume 3, 20-25 June 2004 pp.1957 – 1963.

[8]   Kashif Ishaque, Zainal Salam, Hamed Taheri and Amir Shamsudin 2011 IEEE Applied Power Electronics Colloquium (IAPEC) "Maximum Power Point Tracking for PV System under Partial Shading Condition via Particle Swarm Optimization"

[9]   Saravana Selvan. D, Harikrishnan. V, Umayal. V, Indumathy, " Performance Analysis of slide Mode Control based MPPT Controller for Photovoltaic Applications", in the "International Conference on Advances in Engineering and Technology (ICAET'2014)", Conference proceedings ISBN 978-93-82242-85-7, Singapore on March 29-30, 2014.

[10] Saravana Selvan. D, Mohammed feros khan. J, Umayal. V, Indumathy. M, "Simulation of Fuzzy Logic control based MPPT Technique for Photovoltaic System", in the "2nd International Conference on Innovations in Engineering and Technology (ICCET '2014)", Conference proceedings ISBN 978-81-929653-6-9, Penang on Sept 19-20, 2014.

[11] Kashif Ishaque and Zainal Salam, "A Deterministic Particle Swarm Optimization Maximum Power Point Tracker for Photovoltaic System Under Partial Shading Condition", IEEE transactions on Industrial Electronics, vol. 60, no. 8, august 2013.

[12] Ali Reza Reisi, Mohammad Hassan Moradi, Shahriar Jamasb, "Classification and comparison of maximum power point tracking techniques for photovoltaic system: A review", Science Direct, Renewable and Sustainable Energy Reviews 19 (2013) 433–443.

[13] M.D Goudar, B.P Patil, V. Kumar, " A Review of Improved maximum Peak Power tracking Algorithms For Photovoltaic Systems", International Journal of electrical Engineering and technology (IJEET), ISSN 0976-6545

[14] Masafumi Miyatake, Mummadi Veerachary, Nobuhiko Fujii, Hideyoshi Ko, "Maximum Power Point Tracking of Multiple Photovoltaic Arrays: A PSO Approach" IEEE Transactions on Aerospace and Electronic Systems , 2011, Vol. 47, No. 1.

[15] Yi-Hwa Liu, Shyh-Ching Huang, Jia-Wei Huang, and Wen-Cheng Liang "A Particle Swarm Optimization-Based Maximum Power Point Tracking Algorithm for PV Systems Operating Under Partially Shaded Conditions" IEEE Transactions on Energy Conversion, 2012, Vol. 27, No. 4.

[16] Mahmoud A. Younis , Tamer Khatib, Mushtaq Najeeb, A Mohd Ariffin , "An Improved Maximum Power Point Tracking Controller for PV Systems Using Artificial Neural Network" Przegląd Elektrotechniczny, 2012, R. 88 NR 3b

[17] Whei-Min Lin, Member, IEEE, Chih-Ming Hong, and Chiung-Hsing Chen, "Neural-Network-Based MPPT Control of a Stand-Alone Hybrid Power Generation System" IEEE Transactions on Power Electronics, 2011, Vol. 26, No. 12.

[18] Lian Lian Jiang, Douglas L. Maskell, Jagdish C. Patra , "A Novel Ant Colony optimization based maximum power point tracking for photovoltaic systems under partially shaded conditions, Energy and Buildings"2013, Vol 58. , pp. 227-236.

[19] N. Chai-ead, P. Aungkulanon, and P. Luangpaiboon, Member, IAENG, "Bees and Firefly Algorithms for Noisy Non-Linear Optimization Problems", Proceedings of the 26th International multi Conference of engineers and Computer Scientists, 2011, Volume II.

[20] Surafel Luleseged Tilahun and Hong Choon Ong "Modified Firefly Algorithm" Hindawi Publishing Corporation, Journal of Applied Mathematics, Article ID 467631, 2012, 12 pages

[21] A. Mathew and A. I. Selvakumar, "New MPPT for PV arrays using fuzzy controller in close cooperation with fuzzy cognitive network," IEEE Trans. Energy Conv., 2006, Vol. 21, No. 3, pp. 793–803

[22] C.-S. Chiu, "T-S fuzzy maximum power point tracking control of solar power generation systems," IEEE Trans. Energy Conv., 2010, Vol.25, No. 4, pp. 1123–1132.

[23] Changying Chen, Yue Hong, Hongtu Luo, Huishan Zhao, Chenxiao mo, Qian Fu, Wei Deng, Jinghua Ge, Xi Chen, "Real-time Maximum Power Point Tracking with Single Current Monitoring" in Energy Procedia 2012, International Conference on Future Electrical Power and Energy Systems 2012, pp-783-790.

[24] Yousra Shaiek , Mouna Ben Smida, Anis Sakly, Mohamed Faouzi Mimouni, "Comparison between conventional methods and GA approach for maximum power point tracking of shaded solar PV generators" , Solar Energy , 2013, pp 107-122

[25] K. S. Tey and S. Mekhilef, "Modified incremental conductance algorithm for photovoltaic system under partial shading conditions and load variation," IEEE Transactions on Industrial Electronics, vol. 61, no. 10, pp. 5384–5392, 2014.View at: Publisher Site | Google Scholar

[26] F. A. O. Aashoor and F. V. P. Robinson, "A variable step size perturb and observe algorithm for photovoltaic maximum power point tracking," in 2012 47th International Universities Power Engineering Conference (UPEC), pp. 1–6, London, UK, September 2012.View at: Publisher Site | Google Scholar2017.View at: Publisher Site | Google Scholar

[27] J. Ahmed and Z. Salam, "A modified P&O maximum power point tracking method with reduced steady-state oscillation and improved tracking efficiency," IEEE Transactions on Sustainable Energy, vol. 7, no. 4, pp. 1506–1515, 2016.View at: Publisher Site | Google Scholar

[28] X. S. Li, H. Q. Wen, L. Jiang, W. Xiao, Y. Du, and C. Zhao, "An improved MPPT method for PV system with fast-converging speed and zero oscillation," IEEE Transactions on Industry Applications, vol. 52, no. 6, pp. 5051–5064, 2016.View at: Publisher Site | Google Scholar

[29] H. Abouadane, A. Fakkar, Y. Elkouari, and D. J. E. P. Ouoba, "Performance of a new MPPT method for photovoltaic systems under dynamic solar irradiation profiles," Energy Procedia, vol. 142, pp. 538–544, 2017.View at: Publisher Site | Google Scholar