

Common Fixed Point Theorem For Four Compatible And Subsequentially Continuous Maps In G-Metric Spaces

Jyoti Yadav¹, Balveer singh¹

¹Department of Mathematics

Lords University, Alwar-301028, Rajasthan, India

jyotiy744@gmail.com

drbalveersingh1967@gmail.com

Abstract:

In this manuscript, our aim is to prove a new common fixed point theorem for four compatible and subsequentially continuous (alternately sub compatible and reciprocally continuous) maps in the G-metric spaces satisfying a more generalized contractive condition.

Keywords: *Common fixed point, compatibility, G-metric spaces.*

1. Introduction:

The notion of G-metric spaces was introduced by Mustafa and Sims [6]. After that a lot of authors have worked in this direction [see 7-10].

Following definitions will be used in sequel:

Definition 1.1[6] G-metric spaces:

In 2006, Mustafa and Sims introduced the concept of G-metric space as follows:

Let X be a nonempty set, and let $G : X \times X \times X \rightarrow \mathbb{R}^+$ be a function satisfying the following:

(G1) $G(x, y, z) = 0$ if $x = y = z$,

(G2) $0 < G(x, x, y)$ for all x, y in X with $x \neq y$,

(G3) $G(x, x, y) \leq G(x, y, z)$ for all x, y, z in X with $z \neq y$,

(G4) $G(x, z, y) = G(x, y, z) = G(y, z, x) = \dots$ (symmetry in all three variables),

(G5) $G(x, y, z) \leq G(x, a, a) + G(a, y, z)$ for all x, y, z, a in X (rectangle inequality).

Then the function G is called a G-metric on X and the pair (X, G) is called a G-metric space.

Definition 1.2[6] If $G(x, y, y) = G(y, x, x) \forall x, y \in X$, then (X, G) is called a symmetric G – metric space.

Definition 1.3[1] Let (X, G) be a G- metric space and S and T be two self maps on X . Then S and T are said to be compatible if

$\lim_{n \rightarrow \infty} G(STx_n, TSx_n, TSx_n) = 0$, whenever $\{x_n\}$ is a sequence in X such that

$\lim_{n \rightarrow \infty} Sx_n = \lim_{n \rightarrow \infty} Tx_n = z$ for some $z \in X$.

Definition 1.4[2] Two self mappings S and T are said to be conditionally reciprocally continuous, if whenever the set of sequences $\{x_n\}$ in X satisfying $\lim_{n \rightarrow \infty} Sx_n = \lim_{n \rightarrow \infty} Tx_n$ is nonempty, there exist a sequence $\{y_n\}$ in X satisfying $\lim_{n \rightarrow \infty} Sy_n = \lim_{n \rightarrow \infty} Ty_n = t$ (say) such that $\lim_{n \rightarrow \infty} STy_n = St$ and $\lim_{n \rightarrow \infty} TSy_n = Tt$.

Definition 1.5[2] A pair of self mappings S and T is said to be reciprocally continuous if $\lim_{n \rightarrow \infty} STx_n = St$, $\lim_{n \rightarrow \infty} TSx_n = Tt$ whenever $\{x_n\}$ is a sequence in X such that $\lim_{n \rightarrow \infty} Sx_n = \lim_{n \rightarrow \infty} Tx_n = t$, for some t in X .

Definition 1.6[5] A pair of self mappings S and T is said to be subcompatible if $\lim_{n \rightarrow \infty} Sx_n = t$, $\lim_{n \rightarrow \infty} Tx_n = t$ whenever $\{x_n\}$ is a sequence in X and $\lim_{n \rightarrow \infty} G(STx_n, TSx_n, TSx_n) = 0$.

Definition 1.7[5] A pair of self mappings S and T is said to be subsequentially continuous if $\{x_n\}$ is a sequence in X such that $\lim_{n \rightarrow \infty} Sx_n = \lim_{n \rightarrow \infty} Tx_n = t$ for some t in X such that

$$\lim_{n \rightarrow \infty} STx_n = St, \quad \lim_{n \rightarrow \infty} TSx_n = Tt.$$

2. Main Result

In this section, we shall prove a common fixed point Theorem for four compatible and subsequentially continuous self maps in G-metric spaces.

Theorem 2.1. Let A, B, S and T be four self mappings on a G-metric space (X, G) , and suppose that the pairs (A, S) and (B, T) are compatible and subsequentially continuous (alternately subcompatible and reciprocally continuous) and satisfying the following inequality:

$$G(Ax, By, Bz) \leq p\{G(Sx, Ty, Tz) + G(Ax, Sx, Sx)\} + q\{G(Sx, Ty, Tz) + G(By, Ty, Tz)\} + r \max\left\{G(Sx, Ty, Tz), \frac{G(Sx, By, Bz) + G((Ax, Ty, Tz))}{2}\right\}, \quad (2.1)$$

where $p, q, r > 0$ and $p + q + r < 1$.

Then A, B, S and T have a unique common fixed point in X .

Proof. Given that the pair (A, S) is sequentially continuous and compatible, so there exists a sequence $\{x_n\}$ in X such that $\lim_{n \rightarrow \infty} Ax_n = \lim_{n \rightarrow \infty} Sx_n = z$ for some $z \in X$ and $\lim_{n \rightarrow \infty} G(ASx_n, SAx_n, SAx_n) = G(Az, Sz, Sz) = 0$.

This implies that $Az = Sz$.

Thus z is a coincidence point of the pair (A, S) .

Similarly, the pair (B, T) is sequentially continuous and compatible, so there exists a sequence $\{y_n\}$ in X such that

$$\lim_{n \rightarrow \infty} By_n = \lim_{n \rightarrow \infty} Ty_n = w \text{ for some } w \in X \text{ and}$$

$$\lim_{n \rightarrow \infty} G(BTy_n, TBy_n, TBy_n) = G(Bw, Tw, Tw) = 0.$$

This implies that $Bw = Tw$, that is, w is a coincidence point of the pair (B, T) .

Now, we claim that $z = w$, if $z \neq w$, then using the inequality (2.1) with $x = x_n, y = y_n$ and $z = y_n$,

We have

$$G(Ax_n, By_n, By_n) \leq p\{G(Sx_n, Ty_n, Ty_n) + G(Ax_n, Sx_n, Sx_n)\} + q\{G(Sx_n, Ty_n, Ty_n) + G(By_n, Ty_n, Ty_n)\} + r \max\left\{G(Sx_n, Ty_n, Ty_n), \frac{G(Sx_n, By_n, By_n) + G((Ax_n, Ty_n, Ty_n))}{2}\right\}.$$

Making $n \rightarrow \infty$, we get

$$G(z, w, w) \leq p\{G(z, w, w) + G(z, z, z)\} + q\{G(z, w, w) + G(z, z, z)\}$$

$$\begin{aligned}
 & + r \max \left\{ G(z, w, w), \frac{G(z, w, w) + G((z, w, w))}{2} \right\}, \text{ that is,} \\
 G(z, w, w) & \leq p\{G(z, w, w) + 0\} + q \{G(z, w, w) + 0\} \\
 & + r \max\{G(z, w, w), G(z, w, w)\}, \text{ that is,} \\
 G(z, w, w) & \leq p\{G(z, w, w)\} + q \{G(z, w, w)\} \\
 & + r \{G(z, w, w)\} \\
 & < (p + q + r)\{G(z, w, w)\} \\
 & < \{G(z, w, w)\},
 \end{aligned}$$

a contradiction.

Hence $z = w$.

Now, we prove that $Az = z$.

On the contrary, suppose that, $Az \neq z$.

On making use of the inequality (2.1) with $x = z, y = y_n, z = y_n$, we have

$$\begin{aligned}
 G(Az, By_n, By_n) & \leq p\{G(Sz, Ty_n, Ty_n) + G(Az, Sz, Sz)\} \\
 & + q \{G(Sz, Ty_n, Ty_n) + G(By_n, Ty_n, Ty_n)\} \\
 & + r \max \left\{ G(Sz, Ty_n, Ty_n), \frac{G(Sz, By_n, By_n) + G((Az, Ty_n, Ty_n))}{2} \right\}.
 \end{aligned}$$

Making limit as $n \rightarrow \infty$, we get

$$\begin{aligned}
 G(Az, w, w) & \leq p\{G(Sz, w, w) + G(Az, Az, Az)\} + q \{G(Sz, w, w) + G(w, w, w)\} \\
 & + r \max \left\{ G(Sz, w, w), \frac{G(Sz, w, w) + G((Sz, w, w))}{2} \right\}, \text{ that is,} \\
 G(Az, w, w) & \leq p\{G(Sz, w, w) + 0\} + q \{G(Sz, w, w) + 0\} \\
 & + r \max\{G(Sz, w, w), G(Sz, w, w)\}, \text{ that is,} \\
 G(Az, w, w) & \leq p\{G(Sz, w, w)\} + q \{G(Sz, w, w)\} \\
 & + r \{G(Sz, w, w)\} \\
 & < (p + q + r)\{G(Sz, w, w)\} \\
 & < \{G(Az, w, w)\},
 \end{aligned}$$

a contradiction.

Hence $Az = w = z$.

So $Az = z$.

Now, we claim that $Bz = z$.

Let, if possible, $Bz \neq z$.

Using the inequality (2.1) with $x = x_n, y = z$.

$$\begin{aligned}
 G(Ax_n, Bz, Bz) & \leq p\{G(Sx_n, Tz, Tz) + G(Ax_n, Sx_n, Sx_n)\} \\
 & + q \{G(Sx_n, Tz, Tz) + G(Bz, Tz, Tz)\} \\
 & + r \max \left\{ G(Sx_n, Tz, Tz), \frac{G(Sx_n, Bz, Bz) + G((Ax_n, Tz, Tz))}{2} \right\}.
 \end{aligned}$$

Making limit as $n \rightarrow \infty$, we get

$$\begin{aligned}
 G(z, Bz, Bz) & \leq p\{G(Sz, Tz, Tz) + G(z, z, z)\} + q \{G(z, Tz, Tz) + G(Bz, Tz, Tz)\} \\
 & + r \max \left\{ G(z, Tz, Tz), \frac{G(z, Bz, Bz) + G((z, Tz, Tz))}{2} \right\}. \\
 G(z, Bz, Bz) & \leq p\{G(z, Bz, Bz) + 0\} + q \{G(z, Bz, Bz) + 0\} \\
 & + r \max \left\{ G(z, Bz, Bz), \frac{G(z, Bz, Bz) + G((z, Bz, Bz))}{2} \right\}. \\
 G(z, Bz, Bz) & \leq p\{G(z, Bz, Bz)\} + q \{G(z, Bz, Bz)\} + r \{G(z, Bz, Bz)\} \\
 G(z, Bz, Bz) & \leq (p + q + r)\{G(z, Bz, Bz)\}
 \end{aligned}$$

$$G(z, Bz, Bz) < G(z, Bz, Bz),$$

a contradiction.

Hence $Bz = z$.

So $Az = Bz = Sz = Tz = z$.

Hence z is a common fixed point of the four mappings A, B, S and T .

Uniqueness: Let w be another common fixed point of the mappings A, B, S and T . Then we have $Aw = Bw = Sw = Tw = w$. Now using the inequality (2.1) we have.

$$\begin{aligned} G(z, w, w) = G(Az, Bw, Bw) &\leq p\{G(Sz, Tw, Tw) + G(Az, Sz, Sz)\} \\ &\quad + q\{G(Sz, Tw, Tw) + G(Bw, Tw, Tw)\} \\ &\quad + r \max\left\{G(Sz, Tw, Tw), \frac{G(Sz, Bw, Bw) + G((Az, Tw, Tw))}{2}\right\}. \end{aligned}$$

$$\begin{aligned} G(z, w, w) &\leq p\{G(z, w, w) + G(z, z, z)\} + q\{G(z, w, w) + G(w, w, w)\} \\ &\quad + r \max\left\{G(z, w, w), \frac{G(z, w, w) + G((z, w, w))}{2}\right\}. \end{aligned}$$

$$G(z, w, w) \leq p\{G(z, w, w)\} + q\{G(z, w, w)\} + r \max\{G(z, w, w)\}, \text{ that is,}$$

$$G(z, w, w) \leq (p + q + r)(G(z, w, w)), \text{ that is,}$$

$$G(z, w, w) < (G(z, w, w)),$$

a contradiction. Hence z is a unique common fixed point of the four mappings A, B, S and T .

Now as our supposition the pair (A, S) is subcompatible and reciprocally continuous, then there exists a sequence $\{x_n\}$ in X such that

$$\lim_{n \rightarrow \infty} Ax_n = \lim_{n \rightarrow \infty} Sx_n = z \text{ for some } z \in X \text{ and}$$

$\lim_{n \rightarrow \infty} G(ASx_n, SAx_n, SAx_n) = G(Az, Sz, Sz) = 0$. This implies that $Az = Sz$. That is z is a coincidence point of the pair (A, S)

Similarly, as our supposition that the pair (B, T) is reciprocally continuous and subcompatible, then there exists a sequence $\{y_n\}$ in X such that

$$\lim_{n \rightarrow \infty} By_n = \lim_{n \rightarrow \infty} Ty_n = w \text{ for some } z \in X \text{ and } \lim_{n \rightarrow \infty} G(BTy_n, TBy_n, TBy_n) = G(Bw, Tw, Tw) = 0. \text{ This}$$

implies that $Bw = Tw$. That is w is a coincidence point of the pair (B, T) . The remaining proof is as follows from the upper part.

References

1. B. S. Choudhury, P. Maity, Coupled fixed point results in generalized metric spaces, Math.Comput. Modelling (2011) doi:10.1016/j.mcm2011.01.036.
2. D. K. Patel, P. Kumam, & D. Gopal, Some discussion on the existence of common fixed points for a pair of maps. Fixed Points Theorey Appl 2013, **187**(2013).
3. G. Jungck, Compatible mappings and common fixed points for non continuous non self maps on non metric spaces, Far East J. Math.Sci. **4**(2)1996, 199-215.
4. G. Jungck, Compatible mappings and common fixed points, Int. J.Math. Sci. **9**(4)1986 771-779
5. H. Bouhadjera and C. Godet-Thobie, Common fixed point theorems for pairs of subcompatible maps. Old version, 2009, <http://arxiv.org/abs/0906.3159>.
6. Z. Mustafa and B. Sims, A new approach to generalized metric spaces, Journal of Nonlinear Convex Analysis, **7** (2006), 289-297.
7. Z. Mustafa and B. Sims, Fixed point theorems for contractive mappings in complete G-metric spaces, Fixed Point Theory and Applications, Volume 2009, Article ID 917175.

8. Z. Mustafa, H. Obiedat and F. Awawdeh, Some fixed point theorem for mapping on complete G-metric spaces, *Fixed Point Theory and Applications*, **2008**(2008), Article ID 189870.
9. Z. Mustafa, W. Shatanawi and M. Batineh, Fixed point theorem on uncomplete G-metric spaces, *Journal of Mathematics and Statistics*, **4**(2008), 196-201.
10. Z. Mustafa, W. Shatanawi and M. Batineh, Existence of fixed point results in G-metric spaces, *Int. J. of Math. and Math. Sci.*, **2009**(2009), Article ID 283028.